

Matrices, Vectors; Gauss-Jordan Elimination Suggested Problems Matrix – Vector Notation Back to Solving Linear Systems Summarizing

Matrix Notation — "Encoding" the Information

We realize that all the important information is in the coefficients (numbers), and that the variables (x, y, z) just get carried around. We can "encode" all the information about the linear system

3x -6x 2x	+	21 <i>y</i>	_	3 <i>z</i>	=	0
-6x	_	2 <i>y</i>	_	Ζ	=	62
2 <i>x</i>	—	3 <i>y</i>	+	8 <i>z</i>	=	32

in a matrix

$\underbrace{\left[\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	etimes: $\begin{bmatrix} 3 & 21 & -3 & 0 \\ -6 & -2 & -1 & 62 \\ 2 & -3 & 8 & 32 \end{bmatrix}.$
Augmented Matrix	Augmented Matrix with Coefficient Matrix and right-hand-side "sepa- rated."
Peter Blomgren (blomgren@sdsu.edu)	1.2. Matrices, Vectors,
Matrices, Vectors; Gauss-Jordan Elimination Suggested Problems	Matrix – Vector Notation Back to Solving Linear Systems Summarizing

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[FOCUS :: CS] What is a Matrix?
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From a computer science point-of-view a matrix can be viewed as *data structure*, and depending on your mood (and/or preference of programming paradigm) you can think of it as *e.g.* a

- C—C++ style 2-dimensional array,
 - :: double A[3][3]; /* A is a 3-by-3 matrix */
 - :: A[0][0] = 1; /* Assigning 1 to a_{11} */
 - :: A[2][2] = 14; /* Assigning 14 to a_{33} */
 - :: Yes, some languages count from 0 to (n-1); others from 1 to n.
- or an abstract *container class*.
- Python
 - :: uses (. . .) for immutable "tuples" and [. . .] for "lists" \ldots
 - :: a matrix is a lists-of-lists: [[. . .] , . . . , [. . .]]

Matrix – Vector Notation Back to Solving Linear Systems Summarizing

Row – Column Indexing

Ponder the matrix "A" with 3 rows, and 4 columns:

	3	21	-3	0 -		[a ₁₁	<i>a</i> ₁₂	a ₁₃	a ₁₄ a ₂₄ a ₃₄]
A =	-6	-2	-1	62	=	a ₂₁	a 22	<i>a</i> 23	a ₂₄
	2	-3	8	32 _		a ₃₁	<i>a</i> ₃₂	a ₃₃	a ₃₄]

that is, usually we refer to the entries of a matrix A (upper-case), using double subscripts a_{ij} (lower-case); the subscripts i, and j are "standard" but r (row) and c (column) would be more intuitive.

Sometimes you see the notation $A \in \mathbb{R}^{3 \times 4}$ to denote a 3-by-4 (always [ROWS-by-COLUMNS]) matrix where the entries are real (\mathbb{R}) numbers.

Note: The entries can be other mathematical objects, *e.g.* complex numbers, \mathbb{C} , polynomials, etc... but we will work with \mathbb{R} for quite while.

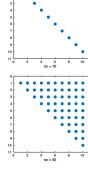
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, Vectors,	— (5/36)	Peter Blomgren (blomgren@sdsu.edu)	1.2. Matrices, Vectors,	— (6/36)
or Notation ng Linear Systems		Matrices, Vectors; Gauss-Jordan Elimination Suggested Problems	Matrix – Vector Notation Back to Solving Linear Systems Summarizing	

Types of Matrices

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- When $A \in \mathbb{R}^{n \times n}$, *i.e.* the matrix has the same number of rows and columns, it is a **square matrix**
- A matrix is diagonal if all entries a_{ij} = 0 for all i ≠ j. (Only entries of the type a_{ii} are non-zero.



 A square matrix is upper triangular if all entries a_{ij} = 0 for all i > j.

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Types of Matrices		Types of Matrices	
 A square matrix is strictly upp gular if all entries a_{ij} = 0 for a A square matrix is lower triang entries a_{ij} = 0 for all i < j. 	all $i \geq j$.	 matrix. A square matrix where all diago off-diagonal entries are <i>zeros</i> 	ero is (surprisingly?) called a zero onal entries are <i>ones</i> , and the $0 \cdots 0 0$ $1 \cdots 0 0$ $\vdots \ddots \vdots \vdots$ $0 \cdots 1 0$ $0 \cdots 0 1$
 A square matrix is strictly low gular if all entries a_{ij} = 0 for a 		is called an identity matrix . "	\cdots " and " \vdots " denote padding with 1-entries; filling the matrix out to its
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Matrices, Vectors; Gauss-Jordan Elimination	Matrix – Vector Notation Back to Solving Linear Systems Summarizing	Matrices, Vectors; Gauss-Jordan Elimination Suggested Problems	Matrix – Vector Notation Back to Solving Linear Systems Summarizing
Matrices of size $n \times 1$ and $1 \times n \Rightarrow$ "N	Vectors"	Vector "Language"	
 A "matrix" with only one colu 	Imn is called a column vector :	k^{th} component of the vector	
$\vec{v} = $	$\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$	 The set (collection) of all (consistence of a set of	\mathbb{R}^2 ; we can
• A "matrix" with only one row	is called a row vector :	origin $(0,0)$ to the point $(x,y) =$	(<i>v</i> ₁ , <i>v</i> ₂):
$ec{w}^{\mathcal{T}}=\left[egin{array}{c} w_1 \end{array} ight.$	$w_2 \cdots w_n$	In the figure we have	
By mathematical convention a vect	tor is a column vector: so \vec{v}	$\vec{u} = \begin{bmatrix} 1\\2 \end{bmatrix}, \vec{v} = \begin{bmatrix} 1\\2 \end{bmatrix}$	$\begin{bmatrix} 1\\3 \end{bmatrix}, \vec{w} = \begin{bmatrix} 2\\2 \end{bmatrix},$

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and \vec{w} are (column) vectors. The notation \vec{w}^T is the *transpose* of the vector \vec{w} , which is a *row vector*.

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 $(x, y) = (v_1, v_2)$ represent the vectors.

Without confusion, we can just let the terminal points

1.2. Matrices, Vectors, ...

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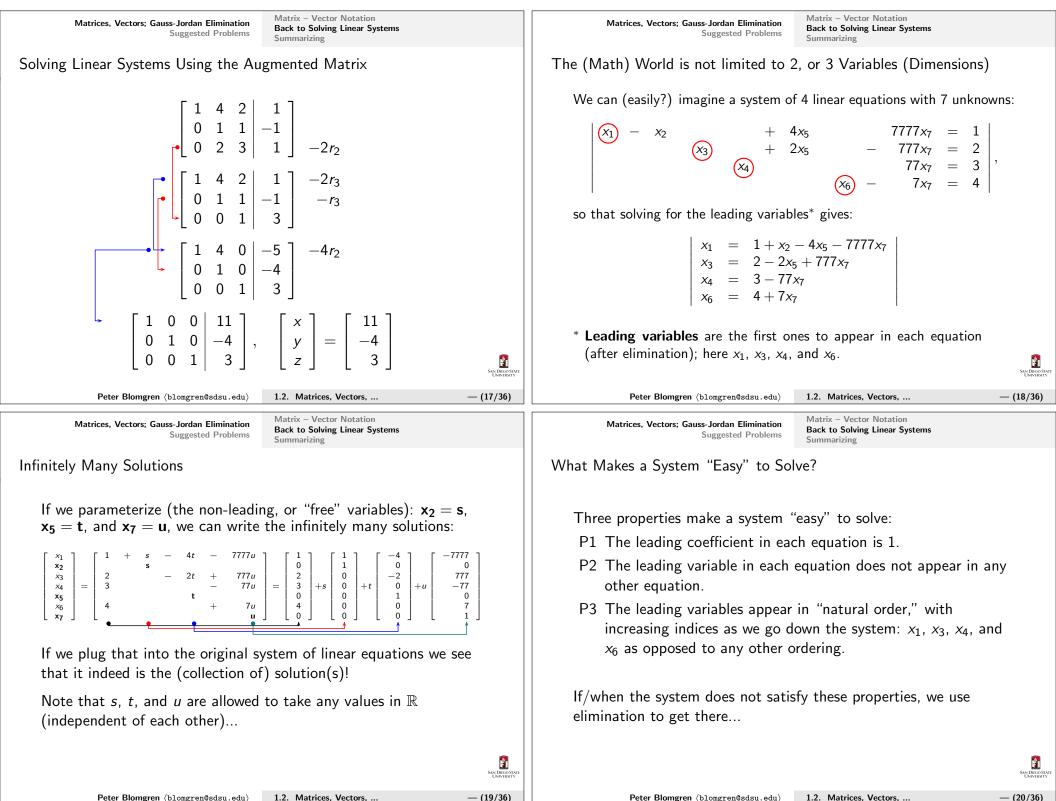
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Matrices, Vectors; Gauss-Jordan Elimination	Matrix – Vector Notation Back to Solving Linear Systems		Matrices, Vectors; Gauss-Jordan Elimination	Matrix – Vector Notation Back to Solving Linear Systems	
Suggested Problems	Summarizing		Suggested Problems	Summarizing	
Adding Vectors			Making Use of our Matrix – Vector N	Notation	
With:			Now, given a linear system:		
$\vec{u} = \begin{vmatrix} 1 \\ 2 \end{vmatrix}, \vec{v} = \end{vmatrix}$	$\begin{vmatrix} 1\\3 \end{vmatrix}, \vec{w} = \begin{vmatrix} 2\\2 \end{vmatrix},$		2x + 8y	+ 4z = 2	
			2x + 5y	$\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	
We can graphically show how to	add vectors:			Ι	
7			We can extract the Coefficient Mat the unknown variables in the system		
6			Г. с. с. с.	, 	
4			2 5	$\begin{array}{c c} 4\\ 1\\ -1 \end{array}$	
3 2			L 4 10	-1	
			or the augmented matrix		
That is	4 6 8		2 8	4 2	
	$ec{u}+ec{v}+ec{w}=\left[egin{array}{c}4\\7\end{array} ight].$			$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	
$u + v = \begin{bmatrix} 5 \end{bmatrix}, t$	$1 + v + w = \begin{bmatrix} 7 \end{bmatrix}$	SAN DIEGO STATE UNIVERSITY	which captures all the information in]	DIEGO STATE
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Matrices Vectors: Gauss- Jordan Elimination	Matrix – Vector Notation		Matrices Vectors: Gauss Jordan Elimination	Matrix – Vector Notation	
Matrices, Vectors; Gauss-Jordan Elimination Suggested Problems	Matrix – Vector Notation Back to Solving Linear Systems Summarizing		Matrices, Vectors; Gauss-Jordan Elimination Suggested Problems		
	Back to Solving Linear Systems			Matrix – Vector Notation Back to Solving Linear Systems Summarizing	
Suggested Problems	Back to Solving Linear Systems		Suggested Problems Solving Linear Systems Using the Au We can solve the linear system by	Matrix – Vector Notation Back to Solving Linear Systems Summarizing	
Suggested Problems The Augmented Matrix	Back to Solving Linear Systems Summarizing		Suggested Problems Solving Linear Systems Using the Au We can solve the linear system by Matrix:	Matrix - Vector Notation Back to Solving Linear Systems Summarizing gmented Matrix y manipulating the Augmented	
Suggested Problems The Augmented Matrix Often, we separate the coefficient	Back to Solving Linear Systems Summarizing		Suggested Problems Solving Linear Systems Using the Au We can solve the linear system by Matrix:	Matrix - Vector Notation Back to Solving Linear Systems Summarizing gmented Matrix y manipulating the Augmented	
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Suggested Problems The Augmented Matrix Often, we separate the coefficient information in the Augmented Ma	Back to Solving Linear Systems Summarizing		Solving Linear Systems Using the Au We can solve the linear system by Matrix: $\begin{bmatrix} 2 & 8 \\ 2 & 5 \\ 4 & 10 & -1 \end{bmatrix}$	Matrix – Vector Notation Back to Solving Linear Systems Summarizing agmented Matrix y manipulating the Augmented $4 \begin{vmatrix} 2 \\ 1 \\ 5 \\ 1 \end{vmatrix} / 2$ $2 \begin{vmatrix} 1 \\ 5 \\ 1 \end{vmatrix} / 2$ $2 \begin{vmatrix} 1 \\ 5 \\ 1 \end{vmatrix} - 2r_1$ $-4r_1$	
Suggested Problems The Augmented Matrix Often, we separate the coefficient information in the Augmented Ma	Back to Solving Linear Systems Summarizing		Solving Linear Systems Using the Au We can solve the linear system by Matrix: $\begin{bmatrix} 2 & 8 \\ 2 & 5 \\ 4 & 10 & -1 \end{bmatrix}$	Matrix – Vector Notation Back to Solving Linear Systems Summarizing agmented Matrix y manipulating the Augmented $4 \begin{vmatrix} 2 \\ 1 \\ 5 \\ 1 \end{vmatrix} / 2$ $2 \begin{vmatrix} 1 \\ 5 \\ 1 \end{vmatrix} / 2$ $2 \begin{vmatrix} 1 \\ 5 \\ 1 \end{vmatrix} - 2r_1$ $-4r_1$	
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Suggested Problems The Augmented Matrix Often, we separate the coefficient information in the Augmented Ma	Back to Solving Linear Systems Summarizing		Solving Linear Systems Using the Au We can solve the linear system by Matrix:	Matrix – Vector Notation Back to Solving Linear Systems Summarizing agmented Matrix y manipulating the Augmented $4 \begin{vmatrix} 2 \\ 1 \\ 5 \\ 1 \end{vmatrix} / 2$ $2 \begin{vmatrix} 1 \\ 5 \\ 1 \end{vmatrix} / 2$ $2 \begin{vmatrix} 1 \\ 5 \\ 1 \end{vmatrix} - 2r_1$ $-4r_1$	

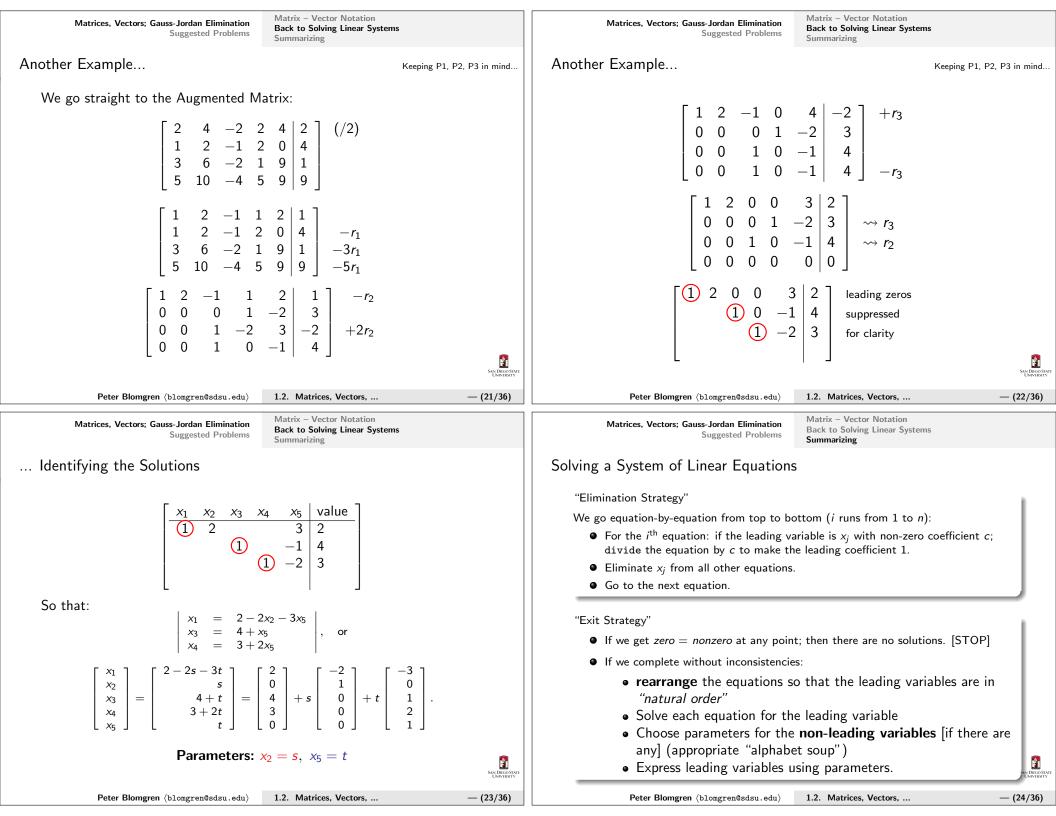
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— (20/36)



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Getting to Reduced Row Echelon Form

Matrix – Vector Notation Back to Solving Linear Systems Summarizing

Elementary Row Operations

Reduced Row Echelon Form

After elimination according to this strategy, the matrix is in:

Reduced Row Echelon Form

A Matrix is said to be in *Reduced Row Echelon Form* if it satisfies the following conditions:

- If a row has non-zero entries, then the first non-zero entry is a 1, called *the leading 1* (or *pivot*) of this row.
- If a column contains a leading 1, then all other entries in that column are 0. [ELIMINATION IS COMPLETE]
- If a row contains a leading 1, then each row above it contains a leading 1 further to the left. [SORTING OF ROWS]

The last condition implies that rows of 0's, if any, must appear at the bottom of the matrix.

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Suggested Problems 1.2

Available on "Learning Glass" videos:

- (1.2.1) Find all solutions to a 2-by-3 linear system using elimination.
- (1.2.3) Find all solutions to a 1-by-3 linear system using elimination.
- (1.2.9) Find all solutions to a 3-by-6 linear system using elimination.
- (1.2.11) Find all solutions to a 4-by-4 linear system using elimination.
- (1.2.18) Determine which matrices are in RREF.
- (1.2.21) Find values of matrix entries so that the resulting matrix is in RREF.



Elementary Row Operations

- Divide a row by a non-zero scalar
- Subtract a multiple of a row from another row
- Swap two rows

This strategy of solving linear systems by reduction to Reduced Row Echelon Form is referred to as **Gaussian Elimination**, or **Gauss-Jordan Elimination**.

Gauss (1777–1855), Jordan (1842–1899); but the Chinese used it looooong before that.

"Gauss-Jordan Elimination" \rightsquigarrow RREF "Gaussian Elimination" \rightsquigarrow REF (leading variables NOT 1's; *LU*-factorization)

— (25/36)	Peter Blomgren (blomgren@sdsu.edu)	1.2. Matrices, Vectors, (26/36)
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Lecture – Book Roadmap

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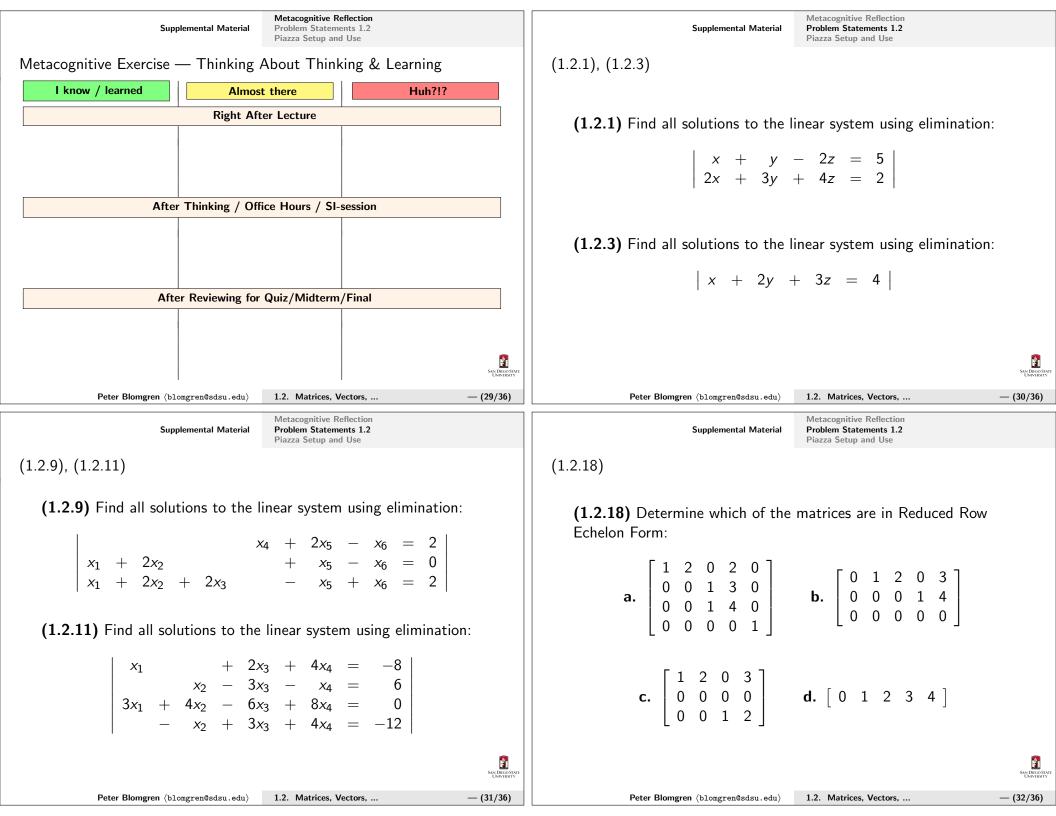
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Lecture	Book, [GS5–]
1.1	§2.2
1.2	§1.1, §1.3, §2.1, §2.3

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Metacognitive Reflection Metacognitive Reflection Supplemental Material Problem Statements 1.2 Supplemental Material Problem Statements 1.2 Piazza Setup and Use Piazza Setup and Use (1.2.21)Does not apply Fall 2021 Piazza Setup and Use, 1 of 3 [TECH::SETUP] **Two Separate Websites** (1.2.21) For which values of a, b, c, d, and e is the following matrix in reduced-row-echelon-form? plazza $\begin{bmatrix} 1 & a & b & 3 & 0 & -2 \\ 0 & 0 & c & 1 & d & 3 \\ 0 & e & 0 & 0 & 1 & 1 \end{bmatrix}$ https://piazza.com/ SAN DIEGO STATE UNIVERSITY • Piazza Account Blackboard at San Diego State University Mini-Quizzes https://Canvas.SDSU.edu/ • Access using app, or GRADEBOOK web interface Ê SAN DIEGO ST. 1.2. Matrices, Vectors, ... - (33/36) 1.2. Matrices, Vectors, ... - (34/36) Peter Blomgren (blomgren@sdsu.edu) Peter Blomgren (blomgren@sdsu.edu) Metacognitive Reflection Metacognitive Reflection Supplemental Material **Problem Statements 1.2** Supplemental Material **Problem Statements 1.2** Piazza Setup and Use Piazza Setup and Use Piazza Setup and Use, 2 of 3 Piazza Setup and Use, 3 of 3 Does not apply Fall 2021 Does not apply Fall 2021 [TECH::SETUP] [TECH::SETUP] Goal: Your Points in the GRADEBOOK! Goal: Your Points in the GRADEBOOK! How do we get there? How do we get there? • Set up a Piazza Account Scores will be transferred after EACH LECTURE You should have gotten an inviatation sent to your • The transfer is manual, so there may be a bit of a delay. [...]@sdsu.edu email address; or go to • https://piazza.com/sdsu/fall2021/math254blomgren If something is not right, please let me know! — Email me! • It is FREE • Download the app from the iOS App Store, or Google Play **2** If you want credit: You can register multiple email addresses If you cannot participate in the use of Piazza (due to lack of a to a piazza account — one of them must match your email suitable device) — let me know, and we'll figure something out. address in Canvas. • In Piazza go to Account/Email Settings **A** Ê SAN DIEGO UNIVER — (35/36) Peter Blomgren (blomgren@sdsu.edu) 1.2. Matrices, Vectors, ... Peter Blomgren (blomgren@sdsu.edu) 1.2. Matrices, Vectors, ... — (36/36)