

Math 254: Introduction to Linear Algebra

Notes #3.3 — Dimension of a Subspace of \mathbb{R}^n

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SLOs 3.3

Dimension of a Subspace of \mathbb{R}^n

After this lecture you should:

- Know that the dimension of a subspace $V \subset \mathbb{R}^n$, is denoted $\dim(V)$; it is a non-negative *integer* counting the number of vectors in (all) bases for V .
- Know that for $V \subset \mathbb{R}^n$, we must have $\dim(V) \leq \dim(\mathbb{R}^n) = n$.
- Know that the trivial subspace has dimension zero: $\dim(\{\vec{0}\}) = 0$.

Common Struggles at This Point

Comment (“Basis for” vs. “Span of” a Vector Space)

The **Basis** is the (minimal) description of the space — given a set of **Basis Vectors**. *Think “building materials.”*

The **Span** of the Basis Vectors (that is the collection of all linear combinations) is the space. *Think “finished product.”*

Comment (Dimension of a Space)

The dimension is always just the count of the number of vectors in the basis — *see today’s lecture!*

How many (non-zero) vectors do we need to describe a subspace?

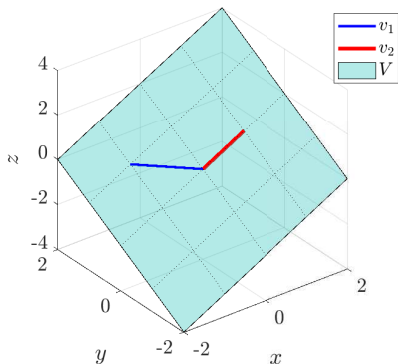


Figure: The two vectors \vec{v}_1 and \vec{v}_2 form a basis of the subspace V . Our geometric intuition, and some vigorous hand-waving, seem to indicate that all bases of a plane V in \mathbb{R}^3 consist of 2 non-parallel vectors.

Maximum Number of Linearly Independent Vectors in a Subspace

Theorem (Proof in [MATH 524 (NOTES#2)])

Consider vectors $\vec{v}_1, \dots, \vec{v}_p$ and $\vec{w}_1, \dots, \vec{w}_q$ in a subspace of \mathbb{R}^n . If the vectors $\vec{v}_1, \dots, \vec{v}_p$ are linearly independent, and the vectors $\vec{w}_1, \dots, \vec{w}_q$ span V , then $q \geq p$.

Comments:

- It is not possible to squeeze more than q linearly independent vectors into the subspace.
- When $q = 2$ (V is a plane), we can have at most 2 linearly independent vectors in the plane.
- We push the proof into the distant future (it's a bit technical and does not necessarily help our intuition; however, we show some related results....)

Number of Vectors in a Basis

Theorem (Number of Vectors in a Basis)

All bases of a subspace V of \mathbb{R}^n consist of the same number of vectors.



Proof :: Number of Vectors in a Basis.

We consider 2 bases $\vec{v}_1, \dots, \vec{v}_p$ and $\vec{w}_1, \dots, \vec{w}_q$ of V . Since $\vec{v}_1, \dots, \vec{v}_p$ are linearly independent (*they're a basis!*), and the vectors $\vec{w}_1, \dots, \vec{w}_q$ span the space (*also a basis!*), we have $q \geq p$ by the theorem on the previous slide.

Flipping the argument, since $\vec{w}_1, \dots, \vec{w}_q$ are linearly independent, and $\vec{v}_1, \dots, \vec{v}_p$ span the space; we must also have $p \geq q$.

We conclude that $p = q$.



The Dimension of a Subspace

Definition (Dimension of a Subspace)

Consider a subspace V of \mathbb{R}^n . The number of vectors in a basis of V is called the *dimension* of V , denoted $\dim(V)$.

Example (The Dimension of \mathbb{R}^n)

The vectors $\vec{e}_1, \dots, \vec{e}_n$ (where $\vec{e}_k \in \mathbb{R}^n$, and only the k^{th} component is non-zero (one)) form a basis for \mathbb{R}^n ; we call this the *standard basis*. As expected, it follows that $\dim(\mathbb{R}^n) = n$.

$$\text{Standard basis for } \mathbb{R}^4: \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Independent Vectors and Spanning Vectors in a Subspace of \mathbb{R}^n

Example (The Dimension of a Plane)

A plane V in \mathbb{R}^n , $n \geq 2$ is two-dimensional. We need exactly two [LINEARLY INDEPENDENT] vectors to describe a plane.

Theorem (Independent Vectors and Spanning Vectors in a Subspace of \mathbb{R}^n)

Consider a subspace V of \mathbb{R}^n , with $\dim(V) = m$.

- We can find at most m linearly independent vectors in V .*
- We need at least m vectors to span V .*
- If m vectors in V are linearly independent, then they form a basis of V .**
- If m vectors in V span V , then they form a basis of V .**

Example: Bases for $\ker(A)$ and $\text{im}(A)$

1 of 5

Example

Find a basis for the kernel, and image, of

$$A = \begin{bmatrix} 1 & 2 & 2 & -5 & 6 \\ -1 & -2 & -1 & 1 & -1 \\ 4 & 8 & 5 & -8 & 9 \\ 3 & 6 & 1 & 5 & -7 \end{bmatrix}$$

The Kernel: We solve $A\vec{x} = \vec{0}$ and get

$$\text{rref}(A) = \begin{bmatrix} 1 & 2 & 0 & 3 & -4 \\ 0 & 0 & 1 & -4 & 5 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}, \quad \text{rank}(A) = 2.$$

The leading ones tell what columns of A contain basis vectors for the *image* of A . [SEE THE NEXT FEW SLIDES]

Example: Bases for $\ker(A)$ and $\text{im}(A)$

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Standard parameterization of the free variables (x_2, x_4, x_5) yield the infinitely many non-trivial solutions for the kernel (see [NOTES#3.1]):

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = s \underbrace{\begin{bmatrix} -2 \\ \textcircled{1} \\ 0 \\ 0 \\ 0 \end{bmatrix}}_{\vec{w}_1} + t \underbrace{\begin{bmatrix} -3 \\ 0 \\ 4 \\ \textcircled{1} \\ 0 \end{bmatrix}}_{\vec{w}_2} + r \underbrace{\begin{bmatrix} 4 \\ 0 \\ -5 \\ 0 \\ \textcircled{1} \end{bmatrix}}_{\vec{w}_3}$$

The vectors \vec{w}_1 , \vec{w}_2 , and \vec{w}_3 are linearly independent (see [LINEAR INDEPENDENCE AND ZERO COMPONENTS (NOTES#3.2)]), and span the kernel.

It follows that \vec{w}_1 , \vec{w}_2 , and \vec{w}_3 form a basis for the kernel of A , and $\dim(\ker(A)) = 3$.

Example: Bases for $\ker(A)$ and $\text{im}(A)$

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The Image: Consider

$$A = \begin{bmatrix} 1 & 2 & 2 & -5 & 6 \\ -1 & -2 & -1 & 1 & -1 \\ 4 & 8 & 5 & -8 & 9 \\ 3 & 6 & 1 & 5 & -7 \end{bmatrix}, \quad B = \text{rref}(A) = \begin{bmatrix} \textcircled{1} & 2 & 0 & 3 & -4 \\ 0 & 0 & \textcircled{1} & -4 & 5 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

3
-4

We quickly see that \vec{b}_1 , and \vec{b}_3 form a basis for $\text{im}(B)$. —: $\vec{b}_2 = \textcircled{2}\vec{b}_1$,
 $\vec{b}_4 = \textcircled{3}\vec{b}_1 - \textcircled{4}\vec{b}_3$, and $\vec{b}_5 = -4\vec{b}_1 + 5\vec{b}_3$.

Also,

$$\textcircled{2}\vec{a}_1 = \begin{bmatrix} 2 \\ -2 \\ 8 \\ 6 \end{bmatrix} = \vec{a}_2, \quad \textcircled{3}\vec{a}_1 - \textcircled{4}\vec{a}_3 = \begin{bmatrix} 3 \\ -3 \\ 12 \\ 9 \end{bmatrix} - \begin{bmatrix} 8 \\ -4 \\ 20 \\ 4 \end{bmatrix} = \begin{bmatrix} -5 \\ 1 \\ -8 \\ 5 \end{bmatrix} = \vec{a}_4$$

Example: Bases for $\ker(A)$ and $\text{im}(A)$

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The Image: Consider

$$A = \begin{bmatrix} 1 & 2 & 2 & -5 & 6 \\ -1 & -2 & -1 & 1 & -1 \\ 4 & 8 & 5 & -8 & 9 \\ 3 & 6 & 1 & 5 & -7 \end{bmatrix}, \quad B = \text{rref}(A) = \begin{bmatrix} 1 & 2 & 0 & 3 & -4 \\ 0 & 0 & 1 & -4 & 5 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

We quickly see that \vec{b}_1 , and \vec{b}_3 form a basis for $\text{im}(B)$. —: $\vec{b}_2 = 2\vec{b}_1$,
 $\vec{b}_4 = 3\vec{b}_1 - 4\vec{b}_3$, and $\vec{b}_5 = -4\vec{b}_1 + 5\vec{b}_3$.
 and finally:

$$-4\vec{a}_1 + 5\vec{a}_3 = \begin{bmatrix} -4 \\ 4 \\ -16 \\ -12 \end{bmatrix} + \begin{bmatrix} 10 \\ -5 \\ 25 \\ 5 \end{bmatrix} = \begin{bmatrix} 6 \\ -1 \\ 9 \\ -7 \end{bmatrix} = \vec{a}_5$$

Example: Bases for $\ker(A)$ and $\text{im}(A)$

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The Image: Consider

$$A = \begin{bmatrix} 1 & 2 & 2 & -5 & 6 \\ -1 & -2 & -1 & 1 & -1 \\ 4 & 8 & 5 & -8 & 9 \\ 3 & 6 & 1 & 5 & -7 \end{bmatrix}, \quad B = \text{rref}(A) = \begin{bmatrix} \boxed{1} & 2 & 0 & 3 & -4 \\ 0 & 0 & \boxed{1} & -4 & 5 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Bottom line: It is easy to see what column vectors are the basis for $\text{im}(\text{rref}(A))$ [and how the other columns are formed from these], once we have identified them; the corresponding ones in A form a basis for $\text{im}(A)$ [and the same linear relations hold for A and $\text{rref}(A)$]; in this case the vectors

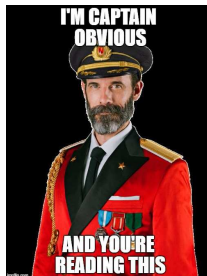
$$\vec{a}_1 = \begin{bmatrix} 1 \\ -1 \\ 4 \\ 3 \end{bmatrix}, \quad \vec{a}_3 = \begin{bmatrix} 2 \\ -1 \\ 5 \\ 1 \end{bmatrix}$$

form a basis for $\text{im}(A)$, and $\dim(\text{im}(A)) = 2$.

Insight :: Row-Reductions and Columns

Insight

Row-reductions DO NOT change the relations between columns.



"Captain Obvious" from <https://imgflip.com/i/1klhm5>, copyright/license unknown.

Using RREF to Construct a Basis of the Image

Theorem (Using RREF to Construct a Basis of the Image)

To construct a *basis of the image* of A , pick the column vectors of A that correspond to the columns of $\text{rref}(A)$ containing leading 1's.



WARNING!



Note that you are picking columns of A (not $\text{rref}(A)$). Generally $\text{im}(A) \neq \text{im}(\text{rref}(A))$.

Dimension of the Image

Theorem (Dimension of the Image)

For any matrix A ,

$$\dim(\text{im}(A)) = \text{rank}(A).$$

If $A \in \mathbb{R}^{n \times m}$:

- the basis of the **kernel** contains as many vectors as there are **free variables**;
- the basis of the **image** contains as many vectors as there are **leading variables**.

This means

$$\dim(\ker(\mathbf{A})) + \dim(\text{im}(\mathbf{A})) = m.$$

Rank-Nullity

a.k.a. The Fundamental Theorem of Linear Transformations

Theorem (Rank-Nullity Theorem)

For any $A \in \mathbb{R}^{n \times m}$, the equation

$$\dim(\ker(A)) + \dim(\operatorname{im}(A)) = m$$

holds. $\dim(\ker(A))$ is called the **nullity of A** ; and we have previously established that $\dim(\operatorname{im}(A)) = \operatorname{rank}(A)$. Thus

$$(\text{nullity of } A) + (\text{rank of } A) = m.$$

This is one of the corner-stone theorems of Linear Algebra.

It reappears in a more general form (The Fundamental Theorem of Linear Maps) in [MATH 524 (NOTES#3.1)].

Orthogonal Projections in the Context of Rank-Nullity

Consider the linear transformation describing the projection onto a plane — $T : \mathbb{R}^3 \rightarrow V$, where V is a plane in \mathbb{R}^3 .

- A plane is spanned by two vectors; $\dim(\text{im}(T)) = 2$
- $\ker(T) = V^\perp = \{\text{the line thru the origin perpendicular to } V\}$;
 $\dim(\ker(T)) = 1$
- We can think of a projection like a “collapse” along the perpendicular direction(s).
- Here we get: $m - \dim(\ker(T)) = \dim(\text{im}(T))$; $(3 - 1 = 2)$.

Note: V^\perp is the collection of all vectors that are orthogonal (perpendicular, \perp) to all vectors in V . In [NOTES#5.1] we will formally define this as the *orthogonal complement* of V .

Another Example

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Example

Find the bases of the image and kernel of the matrix

$$A = \begin{bmatrix} 1 & 2 & 0 & 1 & 2 \\ 1 & 2 & 0 & 2 & 3 \\ 1 & 2 & 0 & 3 & 4 \\ 1 & 2 & 0 & 4 & 5 \end{bmatrix}$$

We can eye-ball and realize that columns #2, #3, and #5 can be written as linear combinations of #1, and #4. But let's pretend we don't see that, and compute

$$\text{rref}(A) = \begin{bmatrix} 1 & 2 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Another Example

2 of 3

We have

$$A = \begin{bmatrix} 1 & 2 & 0 & 1 & 2 \\ 1 & 2 & 0 & 2 & 3 \\ 1 & 2 & 0 & 3 & 4 \\ 1 & 2 & 0 & 4 & 5 \end{bmatrix}, \quad \text{rref}(A) = \begin{bmatrix} 1 & 2 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

So, yeah columns #1 and #4 do indeed form a basis for $\text{im}(A)$, and $\dim(\text{im}(A)) = 2$.

Further, we have

Dependent Vectors	Relation
$\vec{v}_2 = 2\vec{v}_1$	$-2\vec{v}_1 + \vec{v}_2 = \vec{0}$
$\vec{v}_3 = \vec{0}$	$\vec{v}_3 = \vec{0}$
$\vec{v}_5 = \vec{v}_1 + \vec{v}_4$	$-\vec{v}_1 - \vec{v}_4 + \vec{v}_5 = \vec{0}$

Another Example

3 of 3

The three relations define the three vectors spanning the kernel:

Dependent Vectors	Relation
$\vec{v}_2 = 2\vec{v}_1$	$-2\vec{v}_1 + \vec{v}_2 = \vec{0}$
$\vec{v}_3 = \vec{0}$	$\vec{v}_3 = \vec{0}$
$\vec{v}_5 = \vec{v}_1 + \vec{v}_4$	$-\vec{v}_1 - \vec{v}_4 + \vec{v}_5 = \vec{0}$

Kernel vectors:

$$\vec{w}_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{w}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{w}_3 = \begin{bmatrix} -1 \\ 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}$$

so, we have our basis for the kernel; and $\dim(\ker(A)) = 3$;
 $\dim(\text{im}(A)) + \dim(\ker(A)) = 5$

Summarizing the Procedure

Theorem (Finding Bases of the Image and Kernel)

*Identify the dependent columns of A (maybe with the “help” of $\text{rref}(A)$), then:*1 *Identify null-space vectors —*a-i *Express each dependent column as a linear combination of preceding columns*

$$\vec{v}_i = c_1 \vec{v}_1 + \cdots + c_{i-1} \vec{v}_{i-1}$$

a-ii *Write the corresponding relation*

$$-c_1 \vec{v}_1 - \cdots - c_{i-1} \vec{v}_{i-1} + \vec{v}_i = \vec{0}$$

a-iii *Identify the null-space vector*

$$[-c_1 \quad \cdots \quad -c_{i-1} \quad 1 \quad 0 \quad \cdots \quad 0]^T$$

b *(Alternative) Parameterize as usual to get null-space vectors*2 *Collect all such vectors and you have the basis for $\ker(A)$.*3 *The other (independent) columns of A form a basis of $\text{im}(A)$.*

Bases of \mathbb{R}^n

Theorem (Bases of \mathbb{R}^n)

The vectors $\vec{v}_1, \dots, \vec{v}_n$ form a basis of \mathbb{R}^n if and only if the matrix

$$A = [\vec{v}_1 \quad \dots \quad \vec{v}_n]$$

is invertible.

Note: We have n vectors $\in \mathbb{R}^n$, which means $A \in \mathbb{R}^{n \times n}$.

Characteristics of Invertible Matrices

IMPORTANT!

Equivalent Statements: Invertible Matrices

For an $n \times n$ matrix A , the following statements are equivalent; that is for a given A , they are either all true or all false:

- i. A is invertible
- ii. The linear system $A\vec{x} = \vec{b}$ has a unique solution \vec{x} , $\forall \vec{b} \in \mathbb{R}^n$
- iii. $\text{rref}(A) = I_n$
- iv. $\text{rank}(A) = n$
- v. $\text{im}(A) = \mathbb{R}^n$
- vi. $\text{ker}(A) = \{\vec{0}\}$
- vii. The column vectors of A form a basis of \mathbb{R}^n
- viii. The column vectors of A span \mathbb{R}^n
- ix. The column vectors of A are linearly independent

Summary introduced in [NOTES#2.4], added to in [NOTES#3.1]; and will be re-visited again in [NOTES#7.1].

Suggested Problems 3.3

Available on Learning Glass videos:

3.3 — 1, 3, 19, 23, 25, 27, 29, 30, 31, 32

Lecture – Book Roadmap

Lecture	Book, [GS5–]
3.1	§3.1, §3.2, §3.3
3.2	§3.1, §3.2, §3.3, §3.4
3.3	§3.1, §3.2, §3.3, §3.4, §3.5
3.4	

Metacognitive Exercise — Thinking About Thinking & Learning

I know / learned	Almost there	Huh?!?
Right After Lecture		
After Thinking / Office Hours / SI-session		
After Reviewing for Quiz/Midterm/Final		

(3.3.1), (3.3.3)

(3.3.1) Find the linearly dependent (redundant) column vectors; then find a basis for the image of A , and a basis for the kernel of A , where

$$A = \begin{bmatrix} 1 & 3 \\ 2 & 6 \end{bmatrix}.$$

(3.3.3) Find the linearly dependent (redundant) column vectors; then find a basis for the image of A , and a basis for the kernel of A , where

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}.$$

(3.3.19), (3.3.23)

(3.3.19) Find the linearly dependent (redundant) column vectors; then find a basis for the image of A , and a basis for the kernel of A , where

$$A = \begin{bmatrix} 1 & 0 & 5 & 3 & 0 \\ 0 & 1 & 4 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

(3.3.23) Find the reduced row echelon form of A ; then find a basis for the image of A , and a basis for the kernel of A , where

$$A = \begin{bmatrix} 1 & 0 & 2 & 4 \\ 0 & 1 & -3 & -1 \\ 3 & 4 & -6 & 8 \\ 0 & -1 & 3 & 1 \end{bmatrix}.$$

(3.3.25), (3.3.27)

(3.3.25) Find the reduced row echelon form of A ; then find a basis for the image of A , and a basis for the kernel of A , where

$$A = \begin{bmatrix} 1 & 2 & 3 & 2 & 1 \\ 3 & 6 & 9 & 6 & 3 \\ 1 & 2 & 4 & 1 & 2 \\ 2 & 4 & 9 & 1 & 2 \end{bmatrix}.$$

(3.3.27) Determine whether the following vectors form a basis of \mathbb{R}^4 :

$$\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 4 \\ 8 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 4 \\ -8 \end{bmatrix}.$$

(3.3.29), (3.3.30)

(3.3.29) Find a basis of the subspace of \mathbb{R}^3 defined by the equation

$$2x_1 + 3x_2 + x_3 = 0.$$

(3.3.30) Find a basis of the subspace of \mathbb{R}^4 defined by the equation

$$2x_1 - x_2 + 2x_3 + 4x_4 = 0.$$

(3.3.31), (3.3.32)

(3.3.31) Let V be the subspace of \mathbb{R}^4 defined by the equation

$$x_1 - x_2 + 2x_3 + 4x_4 = 0.$$

Find a linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ such that $\ker(T) = \{\vec{0}\}$, and $\text{im}(T) = V$. Describe T by its matrix.

(3.3.32) Find a basis of the subspace of \mathbb{R}^4 that consists of all vectors perpendicular to both

$$\begin{bmatrix} 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}, \quad \text{and} \quad \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix}.$$

Bonus Questions from Reddit

- (a) Show that the kernel of a linear transformation

$$T_A : \mathbb{R}^5 \rightarrow \mathbb{R}^3$$

must have dimension at least 2.

- (b) Show that the image of a linear transformation

$$T_B : \mathbb{R}^3 \rightarrow \mathbb{R}^5$$

must have dimension at most 3.